



AUTOPILOT

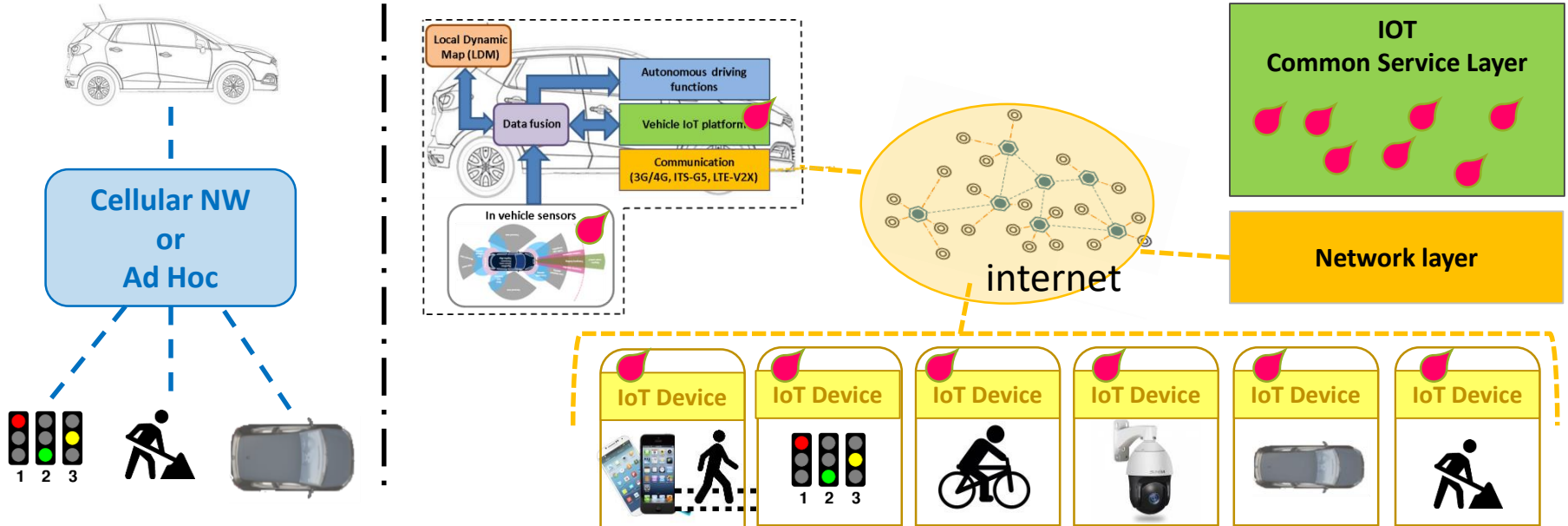
AUTOmated driving **P**rogressed by the
Internet **O**f **T**hings



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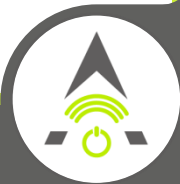


Vehicle centric and Cloud approaches

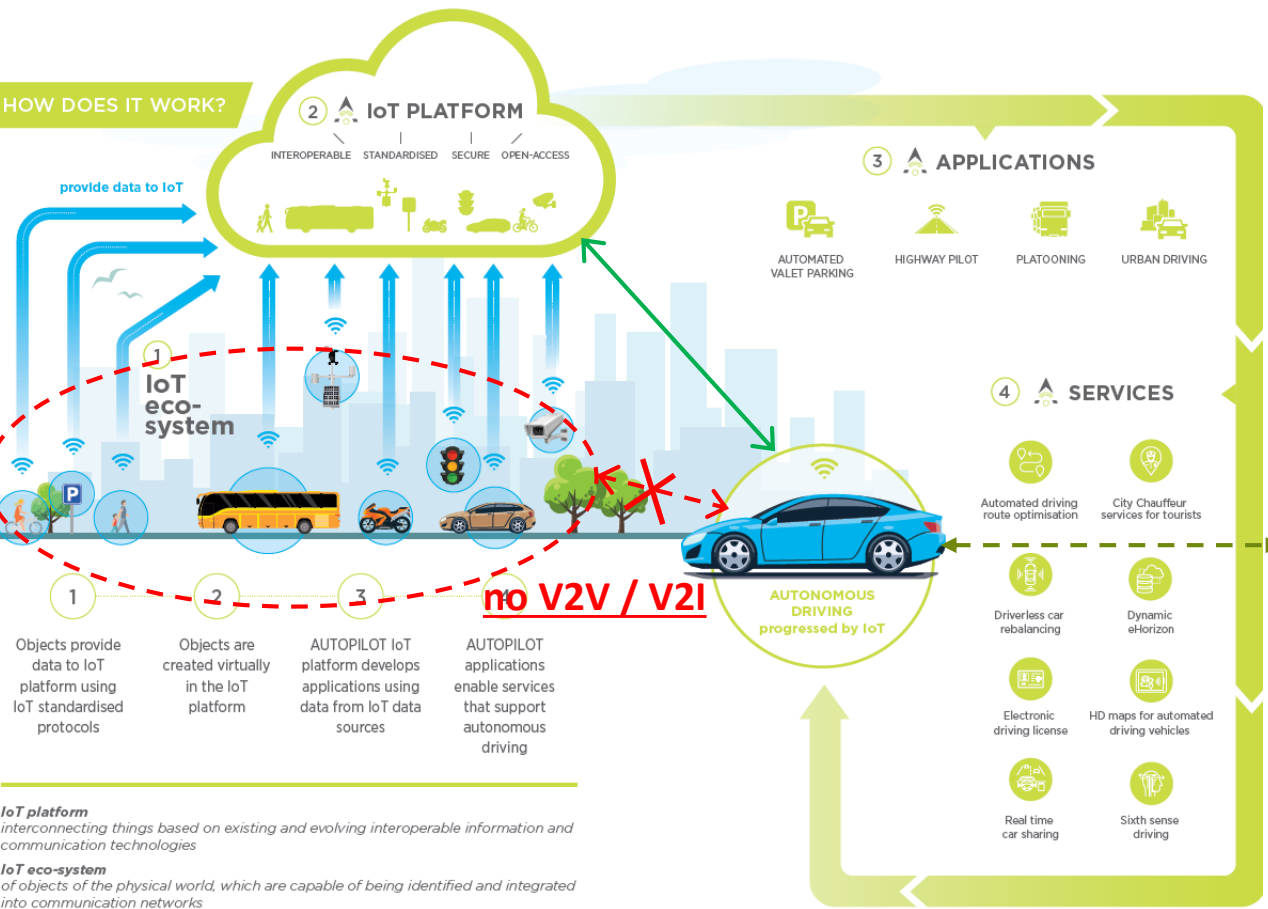


New connectivity paradigm: Cloud and IoT

- V2X approach - vehicle centric
 - limited scope: only device with compatible connectivity
 - Limited functionalities – missing connected devices diversity – “mere” data (no filtering / augmentation)
- Cloud IoT approach – augmented data provided as a service
 - Connectivity agnostic
 - Semantics enhancing device representation (metadata)
 - 2 levels management: device and context
 - “Augmented” data representation out of the context management
 - E.g. traffic jam or other hazards / traffic : environment events from individual Things’ data
 - Easy cross domain service integration - aggregation
 - Standardised data models - platform openness – higher cyber-security



HOW DOES IT WORK?



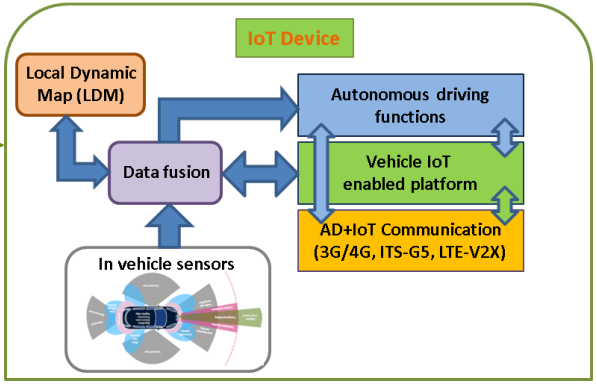
- 1 Objects provide data to IoT platform using IoT standardised protocols
- 2 Objects are created virtually in the IoT platform
- 3 AUTOPILOT IoT platform develops applications using data from IoT data sources
- 4 AUTOPILOT applications enable services that support autonomous driving

IoT platform
interconnecting things based on existing and evolving interoperable information and communication technologies

IoT eco-system
of objects of the physical world, which are capable of being identified and integrated into communication networks

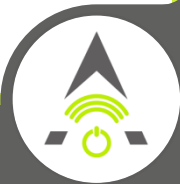
IOT to transform automated driving

Vehicle IoT integration



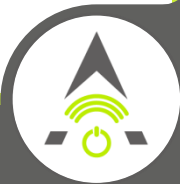
Perspective of IoT for automated driving

- Current use cases (AUTOPILOT)
 - Enhance driving environment perception for the AD DDT and RT HD maps update
 - Provide SaaS/PaaS for mobility (OEM vehicle management platform or MaaS)
- Future usages
 - Driven by usage of AI and data analytics in the IoT cloud platforms
 - Enabled by future Cellular network performances:
 - Massive IOT providing more information for the AD functions – (mMTC)
 - Higher data rates (eMBB) allowing high volume data representation (videos)
 - Lower latency (URLLC) and MEC enabling
 - use of IoT for RT DDT in the vehicle and DDT combined with Infrastructure control



IoT BigData for Automated driving

- Hybrid approach for access to BigData:
 1. Centric approach for OEMs:
 - Sensitive data with relevance only for OEM
 - Contains vehicle specific data
 - Cannot be shared (confidential)
 - Long term relevance for analytics and deep learning for instance
 2. Distributed and open data access
 - Essential for sharing **safety** relevant data (e.g. CAM/DENM data)
 - It is as important for each user that other vehicles get as much useful data as my vehicle get – accident may occur from another vehicle
 - Data consolidation for higher integrity
 - 2 levels of time relevance
 - For open data access – only **short term relevance for cooperative and automated driving**
 - Disable access to “older data”
 - Older data has relevance for **investigation in case of incident/accident**
 - Limited access – only for relevant organisations (police/justice – insurance)
 - Similar as the situation with the signalling data in TelCo networks





Thank you

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